

HSM 09J Data sheet

Electrical data

Value	unit	Pa winding	Ma winding	Kb winding
Number of poles		20	20	20
Number of pole pairs		10	10	10
Inductance/Phase	mH	7.6	2.2	0.6
Resistance/Phase	Ohm	3.7	1.2	0.3
Resistance/Phase-Phase	Ohm	7.4	2.3	0.6
Back EMF/Phase-Phase RMS	Vs/rad	0.69	0.38	0.19
Back EMF @ 1000 rpm	V	72	39	20
Torque constant (RMS)	Nm/A	1.20	0.65	0.33
Max rail voltage	V	750	750	750
Recommended peak current	A	7	14	24
Torque at recommended peak current	Nm	7.35	7.35	7.35

For higher torques, see next page

Mechanical data

Value	unit	Singleturn		Multiturn	
		no brake	brake	no brake	brake
J	kgcm ²	5.1	-	5.5	-
Mass	kg	3.3	-	3.6	-
Len	mm	100.2	-	100.2	-

Insulation class

The insulation system complies with the requirements of EEC LV Directive 73/23/EEC and 93/68/EEC. Test report E9911111E01.

Protection class

HDD motors comply with the requirements for IP-65. IP-67 is available on request.

Thermistor

Overheat protection consists of triple PTC thermistors (one on each phase).

R @ 25 C	100 to 350 Ohm
R @ 145 C	< 1650 Ohm
R @ 155 C	> 4 kOhm

Motor name structure

Type	Flange size	Stator length	Winding	Feedback	Power connector	Brake	Shaft key	Options
HSM	09	- J	- Pa	- ST	- A	- A	- A	- AAA
Type	HSM = Hollow Shaft Motor							
Flange size	Approximate in cm. 09 = 92 mm.							
Stator length	J (shortest), N, Q (longest).							
Winding	Pa suitable for 3000 rpm at rail voltage 560V Ma suitable for 3000 rpm at rail voltage 320V							
Feedback	ST/SN = SinCos single/multiturn.							
Power connector	Many different pinouts available; see www.hdd.se/Connector pin-outs							
Brake	A = no brake (no other option available for HSM motors)							
Shaft key	A (no options available for HSM motors)							
Options	AAA = standard. For other options please contact HDD.							

HDD Servo motors AB

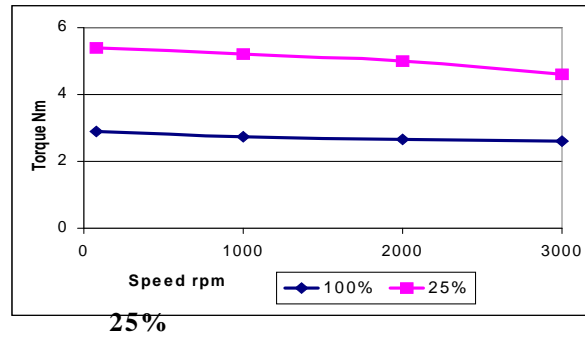
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Torque at 90°C temp rise, in Nm

Speed	Duty cycle	
	100%	25%
100rpm	2.9	5.4
1000rpm	2.8	5.2
2000rpm	2.7	5.0
3000rpm	2.6	4.6



Current at 90°C temp rise, in Ampere rms

Winding	100%			25%		
	Pa	Ma	Kb	Pa	Ma	Kb
locked rotor	2.2	3.9	7.8			
100rpm	2.6	4.4	8.8	4.5	7.9	15.6
1000rpm	2.5	4.3	8.6	4.4	7.7	15.4
3000rpm	2.3	4.0	8.0	4.2	7.3	14.5

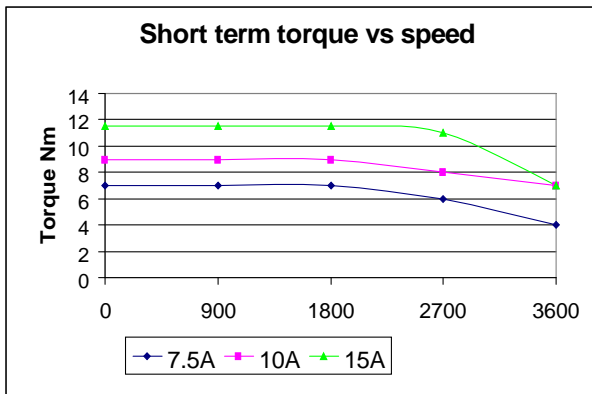
Data were measured on an HSM 09J-Pa series motor mounted on a vertical 260 x 200 x 12 mm aluminum plate in free air, with a winding temperature rise of 90°C and driven by a commercially available inverter. Data for Ma and Kb windings were calculated.

Important note on peak torque and currents

The HSM motors are capable of high peak torques. At very high peak torques the permitted pulse time is very limited as a high current in a very small motor causes rapid temperature rise in the copper winding. The protection thermistor will not react fast enough to protect the winding during high pulse loads. A 10A rms current to a HSM09J-Pa will give some 11.5 Nm, but the copper winding temperature will increase with some 40°C **per second**. This is not a problem for short pulses of < 0.5 seconds as long as the rms value of the current is kept below some 2.7 A. The short term torque graph below represents acceleration ramps at various commanded currents; the actual currents are lower as the driver has not been able to compensate for the high acceleration.

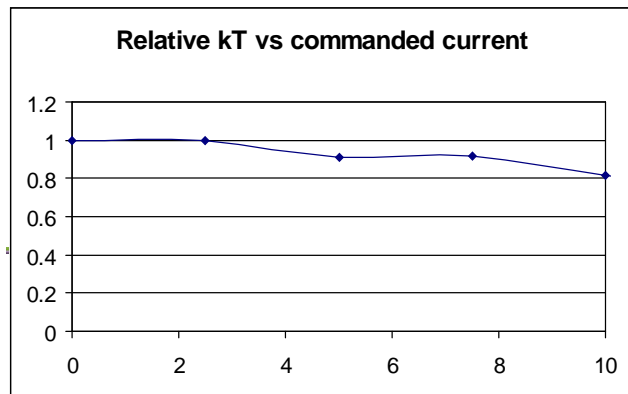
Torque at various commanded currents

HSM 09J-Pa at 560V rail voltage



kT derating factor

Low speed, HSM09J-Pa



Maximum load on shaft at life expectancy 20,000 h

Maximal axial load (push): 1600 N at 500 rpm, 650 N at 3000 rpm.

Maximal axial load (pull): 50 N at all speeds.

Maximal radial load is given by the curves below.

